Matrix-valued Time Series in High Dimension

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- **1** Covariance matrix testing and support recovery: Chap. 2
- 2 Two-Sided Matrix Regression: Chap. 3
- 3 Dynamic Topic Model: Chap. 4 & 5

I Covariance matrix testing and support recovery: Chap. 2

- Introduction: model and objective
- Procedures and theoretical guarantees

2 Two-Sided Matrix Regression: Chap. 3

3 Dynamic Topic Model: Chap. 4 & 5

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Consider X a generic p-dimensional gaussian vector such that $X \sim \mathcal{N}_p(0, \Sigma)$.

• $\Sigma \in \mathcal{S}_p^{++}$ has a Toeplitz structure .

$$\Sigma := \begin{pmatrix} \sigma_0 & \sigma_1 & \sigma_2 & \sigma_3 & \sigma_4 & \cdots & \sigma_{p-1} \\ \sigma_1 & \sigma_0 & \sigma_1 & \sigma_2 & \sigma_3 & \cdots & \sigma_{p-2} \\ \vdots & \ddots & \ddots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \sigma_1 & \sigma_0 & \sigma_1 & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \ddots & \ddots & \vdots \\ \sigma_{p-2} & \cdots & \sigma_3 & \sigma_2 & \sigma_1 & \sigma_0 & \sigma_1 \\ \sigma_{p-1} & \cdots & \sigma_4 & \sigma_3 & \sigma_2 & \sigma_1 & \sigma_0 \end{pmatrix}$$

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- We also develop a procedure that selects non-null correlation coefficients.
- Numerical results illustrate the excellent behaviour of the test procedures and the support selector.

• The one-sided test problem is

$$H_0: \Sigma = I_p, \quad \text{vs. } H_1: \Sigma \in \mathcal{F}_+(s, S, \sigma),$$

where

$$\mathcal{F}_{+}(s, S, \sigma) = \left\{ \Sigma \in \mathcal{S}_{p}^{++} \cap \mathcal{T}_{p} \text{ and } \exists \mathcal{C} \subseteq \{1, \dots, S\}, \\ |\mathcal{C}| = s, \ \forall j \in \{1, p-1\}, \ \begin{array}{l} \sigma_{j} \geq \sigma > 0, \\ \sigma_{j} = 0, \end{array} \right. \begin{array}{l} j \in \mathcal{C}, \\ j \notin \mathcal{C} \end{array} \right\}$$

Testing problems

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• The two-sided test problem is

$$H_0: \Sigma = I_p, \quad \text{vs. } H_1: \Sigma \in \mathcal{F}(s, S, \sigma),$$

where $\mathcal{F}(s, S, \sigma)$ is defined similarly as $\mathcal{F}_+(s, S, \sigma)$ by considering the absolute values of the covariance elements.

Moderately sparse case in the one-sided alternative

• When the alternative is $\mathcal{F}_+(s, S, \sigma)$, we consider for some threshold $t_{n,p}^{MS+}$ the test procedure

$$\Delta_n^{MS+} = \mathbb{1}\left(Sum^+_{\{1:S\}}(\Sigma_n - I_p) \ge t_{n,p}^{MS+}\right),$$

where for an arbitrary set $\mathcal{C} \subseteq \{1, \ldots, S\}$,

$$Sum_{\mathcal{C}}^{+}(\Sigma_n) := \sum_{j \in \mathcal{C}} \operatorname{Tr}(A_j \Sigma_n) = \sum_{j \in \mathcal{C}} \hat{\sigma}_j.$$

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• When the alternative is $\mathcal{F}(s, S, \sigma)$, we consider for some threshold $t_{n,p}^{MS}$ a test Δ_n^{MS} that sums the absolute values of the first S covariance elements of $\Sigma_n - I_p$ and compare it to $t_{n,p}^{MS}$.

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Theorem (B., Butucea, Sorba 2022)

For
$$u > 0$$
, consider $t_{n,p}^{MS+} = \max\left\{\sqrt{\frac{u \cdot S}{n(p-S)}}, \frac{2u \cdot S}{n(p-S)}\right\}$. Then $R(\Delta_n^{MS+}, \mathcal{F}_+) \le 2 \exp\left(-\frac{u}{4}\right)$ provided that $\sigma \ge \frac{2(s+1)}{s} t_{n,p}^{MS+}$.

• When the alternative is $\mathcal{F}_+(s,S,\sigma)$, we consider for some threshold $t_{n,p}^{HS+}$ the test procedure

$$\Delta_n^{HS+} = \max_{\mathcal{C} \subseteq \{1,\ldots,S\}, \#\mathcal{C}=s} \mathbb{1}\left(Sum_{\mathcal{C}}^+(\Sigma_n - I_p) \ge t_{n,p}^{HS+}\right).$$

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• When the alternative is $\mathcal{F}(s, S, \sigma)$, we examine the same procedure by considering the absolute values of the empirical covariance elements.

Highly sparse case in the one-sided alternative

• When the alternative is $\mathcal{F}_+(s, S, \sigma)$, we consider for some threshold $t_{n,p}^{HS+}$ the test procedure

$$\Delta_n^{HS+} = \max_{\mathcal{C} \subseteq \{1,\ldots,S\}, \#\mathcal{C}=s} \mathbb{1} \left(Sum_{\mathcal{C}}^+(\Sigma_n - I_p) \ge t_{n,p}^{HS+} \right).$$

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Theorem (B., Butucea, Sorba 2022)

For
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 $R(\Delta_n^{HS+}, \mathcal{F}^+) \le \exp\left(-(u-1)\log{\binom{S}{s}}\right) + \exp\left(-\frac{u}{4}\right)$ provided that
 $\sigma \ge \frac{1}{s}\left(t_{n,p}^{HS+} + (2s+1)\max\left\{\sqrt{\frac{u \cdot s}{n(p-S)}}, \frac{2u \cdot s}{n(p-S)}\right\}\right)$.

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2 Two-Sided Matrix Regression: Chap. 3

- Introduction
- Prediction for given ranks
- Rank-adaptive and data-driven rank-adaptive procedures

3 Dynamic Topic Model: Chap. 4 & 5

2MR: Consider an observed target matrix Y ∈ ℝ^{n×p} and an observed design matrix X ∈ ℝ^{m×q} following:

$$Y = A^* X B^* + E,$$

where $(A^*, B^*) \in \mathbb{R}^{n \times m} \times \mathbb{R}^{q \times p}$ are low-rank matrix parameters.

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• Limits: MR cannot handle possible correlations among the rows of Y. Need for another matrix parameter A* that left multiplies the signal XB*. If $r := \operatorname{rank} A^* X B^*$ is given, it can be exploited.

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• **Procedure**: Build *r*-dependent explicit predictors satisfying the non-convex constrained minimization problem:

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- Note: rank A^{*}XB^{*} ≤ min(rank A^{*}, rank X, rank B^{*}).
- Global idea: $Y \longrightarrow Y_r \longrightarrow \hat{A}_r X \hat{B}_r$.
- Identifiability: The predictors are not uniquely defined in this setting. Without further strong assumptions, we cannot hope to learn parameters from a non identifiable model.

 $\mathbf{Y} = A^* \mathbf{X} B^* + \mathbf{E}$

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 $\Sigma_Y = U_Y^\top A^* U_X \Sigma_X V_X^\top B^* V_Y + U_Y^\top E V_Y$

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 $\boldsymbol{\Sigma}_{\boldsymbol{Y}} = \left(\boldsymbol{U}_{\boldsymbol{Y}}^{\top}\boldsymbol{A}^{*}\boldsymbol{U}_{\boldsymbol{X}}\right)\boldsymbol{\Sigma}_{\boldsymbol{X}}\left(\boldsymbol{V}_{\boldsymbol{X}}^{\top}\boldsymbol{B}^{*}\boldsymbol{V}_{\boldsymbol{Y}}\right) + \boldsymbol{U}_{\boldsymbol{Y}}^{\top}\boldsymbol{E}\boldsymbol{V}_{\boldsymbol{Y}}$

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$$\Sigma_{Y} = \underbrace{\left(U_{Y}^{\top}A^{*}U_{X}\right)}_{A_{0}^{*}}\Sigma_{X}\underbrace{\left(V_{X}^{\top}B^{*}V_{Y}\right)}_{B_{0}^{*}} + \underbrace{U_{Y}^{\top}EV_{Y}}_{E_{0}}$$

 $Y = A^* X B^* + F$ $U_{\mathbf{Y}} \Sigma_{\mathbf{Y}} V_{\mathbf{Y}}^{\top} = A^* U_{\mathbf{Y}} \Sigma_{\mathbf{Y}} V_{\mathbf{Y}}^{\top} B^* + E$ $\Sigma_{\mathbf{Y}} = U_{\mathbf{Y}}^{\top} A^* U_{\mathbf{Y}} \Sigma_{\mathbf{Y}} V_{\mathbf{Y}}^{\top} B^* V_{\mathbf{Y}} + U_{\mathbf{Y}}^{\top} E V_{\mathbf{Y}}$ $\Sigma_{Y} = \underbrace{\left(U_{Y}^{\top}A^{*}U_{X}\right)}_{A^{*}}\Sigma_{X}\underbrace{\left(V_{X}^{\top}B^{*}V_{Y}\right)}_{B^{*}_{x}} + \underbrace{U_{Y}^{\top}EV_{Y}}_{E_{0}}$ $\Sigma_{Y} = A_0^* \Sigma_{X} B_0^* + E_0$

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One to one mapping between A^*/A_0^* and B^*/B_0^* .

 $\mathbf{Y} = A^* X B^* + F$ $U_{\mathbf{Y}} \Sigma_{\mathbf{Y}} V_{\mathbf{Y}}^{\top} = A^* U_{\mathbf{X}} \Sigma_{\mathbf{X}} V_{\mathbf{Y}}^{\top} B^* + E$ $\Sigma_{\mathbf{Y}} = U_{\mathbf{Y}}^{\top} A^* U_{\mathbf{Y}} \Sigma_{\mathbf{Y}} V_{\mathbf{Y}}^{\top} B^* V_{\mathbf{Y}} + U_{\mathbf{Y}}^{\top} E V_{\mathbf{Y}}$ $\Sigma_{Y} = \underbrace{\left(U_{Y}^{\top}A^{*}U_{X}\right)}_{A^{*}}\Sigma_{X}\underbrace{\left(V_{X}^{\top}B^{*}V_{Y}\right)}_{P^{*}} + \underbrace{U_{Y}^{\top}EV_{Y}}_{F_{*}}$ $\Sigma_Y = A_0^* \Sigma_X B_0^* + E_0$

One to one mapping between A^*/A_0^* and B^*/B_0^* . E_0 and E share the same singular values.

$$\|\boldsymbol{Y} - \boldsymbol{A}\boldsymbol{X}\boldsymbol{B}\|_{F}^{2} = \|\boldsymbol{\Sigma}_{\boldsymbol{Y}} - \boldsymbol{U}_{\boldsymbol{Y}}^{\top}\boldsymbol{A}\boldsymbol{U}_{\boldsymbol{X}}\boldsymbol{\Sigma}_{\boldsymbol{X}}\boldsymbol{V}_{\boldsymbol{X}}^{T}\boldsymbol{B}\boldsymbol{V}_{\boldsymbol{Y}}\|_{F}^{2},$$

because the Frobenius norm being invariant by multiplication of orthogonal matrices.

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This leads to:

$$\|\boldsymbol{Y} - \boldsymbol{A}\boldsymbol{X}\boldsymbol{B}\|_{\boldsymbol{F}}^2 = \|\boldsymbol{\Sigma}_{\boldsymbol{Y}} - \boldsymbol{A}_0\boldsymbol{\Sigma}_{\boldsymbol{X}}\boldsymbol{B}_0\|_{\boldsymbol{F}}^2,$$

where $A_0 = U_Y^\top A U_X$ and $B_0 = V_X^\top B V_Y$.

$$\|\boldsymbol{Y} - \boldsymbol{A}\boldsymbol{X}\boldsymbol{B}\|_{F}^{2} = \|\boldsymbol{\Sigma}_{\boldsymbol{Y}} - \boldsymbol{U}_{\boldsymbol{Y}}^{\top}\boldsymbol{A}\boldsymbol{U}_{\boldsymbol{X}}\boldsymbol{\Sigma}_{\boldsymbol{X}}\boldsymbol{V}_{\boldsymbol{X}}^{\top}\boldsymbol{B}\boldsymbol{V}_{\boldsymbol{Y}}\|_{F}^{2},$$

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$$\|\boldsymbol{Y} - \boldsymbol{A}\boldsymbol{X}\boldsymbol{B}\|_{F}^{2} = \|\boldsymbol{\Sigma}_{\boldsymbol{Y}} - \boldsymbol{A}_{0}\boldsymbol{\Sigma}_{\boldsymbol{X}}\boldsymbol{B}_{0}\|_{F}^{2},$$

where $A_0 = U_Y^\top A U_X$ and $B_0 = V_X^\top B V_Y$. A and A_0 have the same rank, idem for B and B_0 . The initial problem is equivalent to finding predictors satisfying

$$(\hat{A}_{0r}, \hat{B}_{0r}) \in \underset{\substack{A_0, B_0:\\ \operatorname{rank} A_0 \wedge \operatorname{rank} B_0 \leq r}}{\operatorname{arg\,min}} \|\Sigma_Y - A_0 \Sigma_X B_0\|_F^2.$$

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• How far is the predictor $\hat{A}_{0r} \Sigma_X \hat{B}_{0r}$ from the signal $A^* X B^*$?

Theorem (B., Butucea 2023)

The predictor $\hat{A}_{0_r} \Sigma_X \hat{B}_{0_r}$ satisfies for C > 0 and for any t > 0:

$$\begin{split} \|A_0^* \Sigma_X B_0^* - \hat{A_0}_r \Sigma_X \hat{B_0}_r\|_F^2 \leq &9 \inf_{\substack{A_0, B_0: \\ \operatorname{rank} A_0 \wedge \operatorname{rank} B_0 \leq r \\ + C\sigma^2 (1+t)^2 \cdot r(n+p), \end{split}$$

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- \$\mathcal{O}(r(n+p))\$ is the minimax optimal rate in the (one-sided) matrix regression (MR) model.
- From the explicit solutions (Â_{0r}, B̂_{0r}) we deduce (Â_r, B̂_r) solution to the initial problem:

$$\hat{A}_r = U_Y \hat{A}_{0r} U_X^\top$$
 and $\hat{B}_r = V_X \hat{B}_{0r} V_Y^\top$.

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Simulation results confirm the good prediction and the rank consistency results under data-driven explicit choices of the tuning parameters and the scaling parameter of the noise.
1 Covariance matrix testing and support recovery: Chap. 2

2 Two-Sided Matrix Regression: Chap. 3

3 Dynamic Topic Model: Chap. 4 & 5

- Introduction: Topic Models, Identifiability, Dynamic.
- Dynamic Latent Factors: Procedure and theoretical guarantees
- Dynamic Topic Model: Procedure and theoretical guarantees

Given a dictionary of p words we observe n documents.

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$$\mathbb{P}(\text{word } i | \text{document } j) = \sum_{k=1}^{K} \mathbb{P}(\text{word } i | \text{topic } k) \mathbb{P}(\text{topic } k | \text{document } j)$$

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NMF bibliography:

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- Direct estimation of W^* is studied in Klopp, Panov, Sigalla, Tsybakov 2023 (Ann. Statist.) under the anchor document assumption.

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Double randomness: Dirichlet + Multinomial

Nayel, Bettache

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capture the affinity of topics to be covered together in the same document. **Assume**: $\lambda_{\mathcal{K}}(\Sigma_{\mathcal{W}}^{1:\mathcal{T}}) \ge c > 0$, a.s.. Remark: if $\min_k \tilde{\theta}_k^* \ge c > 0$, this holds for large enough n, \mathcal{T} with high probability.

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- For $\underline{\theta}$ and m in (0,1) and $\Sigma(\theta^*) = \frac{1}{\alpha+1} \left(\operatorname{diag}(\tilde{\theta}^*) \tilde{\theta}^* \cdot (\tilde{\theta}^*)^\top \right)$, θ^* satisfies:

 $\min_{k \in [K]} \tilde{\theta}^*(k) \geq \underline{\theta} \text{ and } m \leq \mathsf{Tr}(\Sigma(\theta^*)) \leq 1.$

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Then $W^{1;T}$ is recovered by projection of $\Pi^{1;T}$ onto the span of A^* .

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SVD: of Π_{*} := UΣV^T which satisfies rank(Π_{*}) = K a.s..
 Perron-Frobenius's theorem guarantees that [U]_{.1} does not possess any null entry a.s.. The SVD creates a low dimensional word embedding into ℝ^K but these vectors do not directly lead to the recovery of A^{*}.

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- Post-SVD normalization: Compute $\mathbf{R} \in \mathbb{R}^{p \times (K-1)}$: for $i \in [p]$ and $k \in [K - 1],$

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Given Π^{1:T}, A* is exactly recovered following these steps (Ke, Wang 2024): *Pre-SVD normalization:* Compute Π_{*} := M^{-1/2}_{*}Π^{1:T} where

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- *SVD:* of $\Pi_* := \boldsymbol{U} \boldsymbol{\Sigma} \boldsymbol{V}^\top$ which satisfies rank $(\Pi_*) = K$ a.s..
- Post-SVD normalization: Compute $\mathbf{R} \in \mathbb{R}^{p \times (K-1)}$: for $i \in [p]$ and $k \in [K-1]$,

$$[\boldsymbol{R}]_{ik} = rac{[\boldsymbol{U}]_{i(k+1)}}{[\boldsymbol{U}]_{i1}}$$

 $[\mathbf{R}]_{1.},\ldots,[\mathbf{R}]_{p.}$ are located in a simplex

$$G_{\boldsymbol{\eta}} := \left\{ x : x = \sum_{k=1}^{K} \alpha_k \boldsymbol{\eta}_k, \ \forall k \in [K], \ \alpha_k \ge 0 \ \sum_{k=1}^{K} \alpha_k = 1 \right\}.$$

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$$[\boldsymbol{R}]_{i.} = \sum_{k=1}^{K} [\boldsymbol{\Lambda}]_{ik} \boldsymbol{\eta}_{k},$$

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Word-topic matrix estimation: Define Γ := M_{*}^{1/2}diag([U]_{.1})Λ. Normalize each column of Γ by its L₁ norm. The resulting matrix is A^{*}.

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Dynamic Latent Factors: Estimators

• We define $\hat{\theta}$, estimator of $\tilde{\theta}^*$, as the empirical mean of the recovered $\left(W_j^{t+1}\right)_{j,t}$:

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• We estimate $1 - c^*$ by the normalized sum of scalar products:

$$\widehat{(1-c)} := \frac{\sum\limits_{t=1}^{T-1} \sum\limits_{j=1}^{n} \left\langle W_{j}^{t+1} - \overline{W}^{t+1}; W_{j}^{t} - \overline{w} \right\rangle}{\sum\limits_{t=1}^{T-1} \sum\limits_{j=1}^{n} \left\| W_{j}^{t} - \overline{W} \right\|_{2}^{2}},$$

$$\overline{W}^{+1} := \frac{1}{n(T-1)} \sum_{t=1}^{T-1} \sum_{j=1}^{n} W_{j}^{t+1} \text{ and } \overline{W} := \frac{1}{n(T-1)} \sum_{t=1}^{T-1} \sum_{j=1}^{n} W_{j}^{t}.$$

Using the variance of the stationary sequence and the explicit expression of the matrix $\boldsymbol{\Sigma},$ we see that:

$$\operatorname{Tr}(\mathbb{V}(w_j^t)) = rac{c^*}{2-c^*} rac{1-\| ilde{ heta}^*\|_2^2}{lpha+1}.$$

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$$\hat{\alpha} = \frac{\hat{c}}{2-\hat{c}} \frac{1-\|\hat{\theta}\|_2^2}{\mathcal{V}} - 1, \quad \text{where} \quad \mathcal{V} := \frac{1}{n(\mathcal{T}-1)} \sum_{t=1}^{\mathcal{T}-1} \sum_{j=1}^n \left\| w_j^t - \overline{w} \right\|_2^2.$$

For any N, n and T large enough, with probability at least $1 - \frac{C_1}{nT}$:

$$\max\left\{\left\|\hat{\theta}-\tilde{\theta}^*\right\|_2, |\widehat{(1-c)}-(1-c^*)|, |\hat{\alpha}-\alpha^*|\right\} \le C_2 \cdot \sqrt{\frac{\log(nT)}{n(T-1)}},$$

where C_1 , $C_2 > 0$ are explicit constants, free of the dimensions appearing in the model.

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- Solution of $[\hat{U}]_{.1}, \ldots, [\hat{U}]_{.K}$ from $[\boldsymbol{U}]_{.1}, \ldots, [\boldsymbol{U}]_{.K}$
- Sehaviour of the vertex hunting algorithm with noisy entries.

For N, n and T large enough, there exists χ , a positive constant only depending on K, such that with probability at least $1 - \frac{8}{nT}$:

$$\sum_{i=1}^{p} \left\| [\hat{A}]_{i.} - [A^*]_{i.} \right\|_1 \leq \chi \sqrt{\frac{p \log(nT) + p^2}{nT(N-2)}} p(1+p)(1+\max_{x \in \mathcal{G}_{\eta}} \|x\|_2).$$

For N, n and T large enough, and fixed number of topics K and of the vocabulary size p, with probability at least $1 - \frac{C}{nT}$:

$$\begin{split} &\max\left\{\left\|\hat{\theta} - \tilde{\theta}^*\right\|_2, |\widehat{(1-c)} - (1-c^*)|, |\hat{\alpha} - \alpha^*|\right\} \\ &\leq \mathcal{O}\left(\sqrt{\frac{\log(nT)}{n(T-1)}} + \sqrt{\frac{\log(nT)}{N}}\right). \end{split}$$

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The bounds are driven by the Dirichlet noise and by the multinomial noise.