Matrix-valued Time Series in High Dimension

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1 [Covariance matrix testing and support recovery: Chap. 2](#page-2-0)

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Consider X a generic p−dimensional gaussian vector such that $X \sim \mathcal{N}_p(0, \Sigma)$.

 $\Sigma \in \mathcal{S}^{++}_\rho$ has a Toeplitz structure .

$$
\Sigma := \begin{pmatrix}\n\sigma_0 & \sigma_1 & \sigma_2 & \sigma_3 & \sigma_4 & \cdots & \sigma_{p-1} \\
\sigma_1 & \sigma_0 & \sigma_1 & \sigma_2 & \sigma_3 & \cdots & \sigma_{p-2} \\
\vdots & \vdots & \ddots & \vdots & \ddots & \vdots & \vdots \\
\vdots & \vdots & \ddots & \vdots & \ddots & \vdots & \vdots \\
\sigma_{p-2} & \cdots & \sigma_3 & \sigma_2 & \sigma_1 & \sigma_0 & \sigma_1 \\
\sigma_{p-1} & \cdots & \sigma_4 & \sigma_3 & \sigma_2 & \sigma_1 & \sigma_0\n\end{pmatrix}
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- This is analogous to but more general than the detection of sparse Gaussian means: Ingster 2001, 2002 (Math. Methods Statist.) and Donoho, Jin 2004 (Ann. Statist.)
- We also develop a procedure that selects non-null correlation coefficients.
- Numerical results illustrate the excellent behaviour of the test procedures and the support selector.

• The one-sided test problem is

$$
H_0: \Sigma = I_p, \quad \text{vs. } H_1: \Sigma \in \mathcal{F}_+(s, S, \sigma),
$$

where

$$
\mathcal{F}_+(s, S, \sigma) = \left\{ \Sigma \in \mathcal{S}_p^{++} \cap \mathcal{T}_p \text{ and } \exists \mathcal{C} \subseteq \{1, \ldots, S\}, \right\}
$$

$$
|\mathcal{C}| = s, \ \forall j \in \{1, p-1\}, \ \frac{\sigma_j \ge \sigma > 0, \qquad j \in \mathcal{C}, \beta \in \mathcal{C} \cap \mathcal{
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• The two-sided test problem is

$$
H_0: \Sigma = I_p, \quad \text{vs. } H_1: \Sigma \in \mathcal{F}(s, S, \sigma),
$$

where $\mathcal{F}(s, S, \sigma)$ is defined similarly as $\mathcal{F}_+(s, S, \sigma)$ by considering the absolute values of the covariance elements.

Moderately sparse case in the one-sided alternative

When the alternative is $\mathcal{F}_+(\pmb{s}, \pmb{S}, \sigma)$, we consider for some threshold $t_{n,\rho}^{MS+}$ the test procedure

$$
\Delta_n^{MS+} = \mathbb{1} \left(Sum_{\{1:S\}}^+(\Sigma_n - I_p) \geq t_{n,p}^{MS+} \right),
$$

where for an arbitrary set $C \subseteq \{1, \ldots, S\}$,

$$
Sum_{\mathcal{C}}^+(\Sigma_n) := \sum_{j \in \mathcal{C}} \text{Tr}(A_j \Sigma_n) = \sum_{j \in \mathcal{C}} \hat{\sigma}_j.
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When the alternative is $\mathcal{F}(s, S, \sigma)$, we consider for some threshold $t_{n, p}^{MS}$ a test Δ_n^{MS} that sums the absolute values of the first S covariance elements of $\Sigma_n - I_p$ and compare it to $t_{n,p}^{MS}$.

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Theorem (B., Butucea, Sorba 2022)

For
$$
u > 0
$$
, consider $t_{n,p}^{MS+} = \max \left\{ \sqrt{\frac{u \cdot S}{n(p- S)}}, \frac{2u \cdot S}{n(p- S)} \right\}$. Then
\n $R(\Delta_n^{MS+}, \mathcal{F}_+) \le 2 \exp\left(-\frac{u}{4}\right)$ provided that $\sigma \ge \frac{2(s+1)}{s} t_{n,p}^{MS+}$.

When the alternative is $\mathcal{F}_+(s, S, \sigma)$, we consider for some threshold $t^{HS+}_{n,p}$ the test procedure

$$
\Delta_n^{HS+} = \max_{C \subseteq \{1,\ldots,S\}, \#C=s} \mathbb{1} \left(Sum_C^+(\Sigma_n - I_p) \geq t_{n,p}^{HS+} \right).
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• When the alternative is $\mathcal{F}(s, S, \sigma)$, we examine the same procedure by considering the absolute values of the empirical covariance elements.

Highly sparse case in the one-sided alternative

When the alternative is $\mathcal{F}_+(s, S, \sigma)$, we consider for some threshold $t^{HS+}_{n,p}$ the test procedure

$$
\Delta_n^{HS+} = \max_{\mathcal{C} \subseteq \{1,\ldots,S\}, \#\mathcal{C}=s} \mathbb{1} \left(\mathcal{S}um_{\mathcal{C}}^+(\Sigma_n - I_p) \geq t_{n,p}^{HS+} \right).
$$

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Theorem (B., Butucea, Sorba 2022)

For
$$
u > 1
$$
, consider $t_{n,p}^{HS+} = \max \left\{ \sqrt{\frac{4u \cdot s \log {s \choose s}}{n(p-S)}}, \frac{8u \cdot s \log {s \choose s}}{n(p-S)} \right\}$. Then
\n
$$
R(\Delta_n^{HS+}, \mathcal{F}^+) \le \exp \left(-(u-1) \log {s \choose s} \right) + \exp \left(-\frac{u}{4} \right) \text{ provided that}
$$
\n
$$
\sigma \ge \frac{1}{s} \left(t_{n,p}^{HS+} + (2s+1) \max \left\{ \sqrt{\frac{u \cdot s}{n(p-S)}}, \frac{2u \cdot s}{n(p-S)} \right\} \right).
$$

1 [Covariance matrix testing and support recovery: Chap. 2](#page-2-0)

² [Two-Sided Matrix Regression: Chap. 3](#page-22-0)

- **[Introduction](#page-23-0)**
- **[Prediction for given ranks](#page-38-0)**
- [Rank-adaptive and data-driven rank-adaptive procedures](#page-65-0)

3 [Dynamic Topic Model: Chap. 4 & 5](#page-72-0)

2MR: Consider an observed target matrix $Y \in \mathbb{R}^{n \times p}$ and an observed design matrix $X \in \mathbb{R}^{m \times q}$ following:

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Y=A^*XB^*+E,
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where $(A^*, B^*) \in \mathbb{R}^{n \times m} \times \mathbb{R}^{q \times p}$ are low-rank matrix parameters.

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 \bullet Limits: MR cannot handle possible correlations among the rows of Y. Need for another matrix parameter A^* that left multiplies the signal XB^* . If $r := \text{rank } A^* X B^*$ is given, it can be exploited.

Procedure: Build r-dependent explicit predictors satisfying the non-convex constrained minimization problem:

$$
(\hat{A}_r, \hat{B}_r) \in \underset{A, B:}{\arg \min} \|Y - AXB\|_F^2.
$$

\n
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- Global idea: $Y \longrightarrow Y_r \longrightarrow \hat{A}_r X \hat{B}_r$.
- Identifiability: The predictors are not uniquely defined in this setting. Without further strong assumptions, we cannot hope to learn parameters from a non identifiable model.

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 $\Sigma_{Y}=\left(U_{Y}^{\top}A^{*}U_{X}\right) \Sigma_{X}\left(V_{X}^{\top}B^{*}V_{Y}\right) +U_{Y}^{\top}EV_{Y}$

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One to one mapping between A^*/A_0^* and B^*/B_0^* .

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One to one mapping between A^*/A_0^* and B^*/B_0^* . E_0 and E share the same singular values.

$$
||Y - AXB||_F^2 = ||\Sigma_Y - U_Y^\top A U_X \Sigma_X V_X^\top B V_Y||_F^2,
$$

because the Frobenius norm being invariant by multiplication of orthogonal matrices.

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This leads to:

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where $A_0 = U_Y^{\top} A U_X$ and $B_0 = V_X^{\top} B V_Y$.

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where $A_0 = U_Y^{\top} A U_X$ and $B_0 = V_X^{\top} B V_Y$. A and A_0 have the same rank, idem for B and B_0 . The initial problem is equivalent to finding predictors satisfying

$$
\big(\hat{A_0}_r,\hat{B_0}_r\big)\in \underset{\substack{A_0,B_0:\\ \mathop{\mathrm{rank}}\nolimits A_0\wedge\mathop{\mathrm{rank}}\nolimits B_0\leq r}}{\arg\min} \| \Sigma_Y-A_0\Sigma_X B_0\|_F^2.
$$

Solution of D2MR

Objective: Under the constraint rank(A_0) $\leq r$ and rank(B_0) $\leq r$, minimize:

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Solution of D2MR

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• Solution:

How far is the predictor \hat{A}_0 , $\Sigma_X \hat{B_0}$, from the signal A^*XB^* ?

Theorem (B., Butucea 2023)

The predictor \hat{A}_0 , $\Sigma_X \hat{B}_0$, satisfies for $C > 0$ and for any $t > 0$:

$$
||A_0^* \Sigma_X B_0^* - \hat{A}_0 \Sigma_X \hat{B}_0 \Sigma_Y||_F^2 \leq 9 \inf_{\substack{A_0, B_0:\\ \text{rank } A_0 \wedge \text{rank } B_0 \leq r}} ||A_0^* \Sigma_X B_0^* - A_0 \Sigma_X B_0||_F^2 + C \sigma^2 (1+t)^2 \cdot r(n+p),
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with probability larger than 1 – 2 $\exp(-t^2(\sqrt{n} + \sqrt{p})^2)$.

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 $||A^*XB^* - AXB||_F^2 = \sum_{k=r+1}^{r^*} σ_k (A^*XB^*)^2 \cdot \mathbf{1}_{r < r^*}.$ \bullet inf A,B rank A∧rank B≤r

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- \circ $\mathcal{O}(r(n+p))$ is the minimax optimal rate in the (one-sided) *matrix regression* (MR) model.
- From the explicit solutions $(\hat{A}_0, \hat{B}_0, r)$ we deduce (\hat{A}_r, \hat{B}_r) solution to the initial problem:

$$
\hat{A}_r = U_Y \hat{A}_{0r} U_X^\top \quad \text{and} \quad \hat{B}_r = V_X \hat{B}_{0r} V_Y^\top.
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Simulation results confirm the good prediction and the rank consistency results under data-driven explicit choices of the tuning parameters and the scaling parameter of the noise.
1 [Covariance matrix testing and support recovery: Chap. 2](#page-2-0)

² [Two-Sided Matrix Regression: Chap. 3](#page-22-0)

3 [Dynamic Topic Model: Chap. 4 & 5](#page-72-0)

- **[Introduction: Topic Models, Identifiability, Dynamic.](#page-73-0)**
- [Dynamic Latent Factors: Procedure and theoretical guarantees](#page-105-0)
- **[Dynamic Topic Model: Procedure and theoretical guarantees](#page-131-0)**

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\mathbb{P}(\text{word } i | \text{document } j) = \sum_{k=1}^{K} \mathbb{P}(\text{word } i | \text{topic } k) \mathbb{P}(\text{topic } k | \text{document } j)
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NMF bibliography:

NMF is NP-hard: Vavasis 2010 (SIAM J Optim.).

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- Direct estimation of W^* is studied in Klopp, Panov, Sigalla, Tsybakov 2023 (Ann. Statist.) under the anchor document assumption.

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where $c^* \in (0,1)$, and each $\bm{\Delta}^t \in \mathbb{R}^{K \times n}$ has i.i.d. columns sampled from the Dirichlet distribution $\mathcal{D}(\theta^*)$ with $\theta^* \in \mathbb{R}_+^K$.

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Double randomness: Dirichlet $+$ Multinomial

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where $H := diag(h_1, \ldots, h_p)$ and $h_i := ||A_i^*||_1$. **Assume**: $\lambda_K(\Sigma_A) \ge c$, $\min_{k,l} [\Sigma_A]_{kl} \ge c$ and $\min_i h_i := h_{\min} \ge c \frac{K}{p}$ $\frac{\cdot}{p}$.

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capture the affinity of topics to be covered together in the same document. **Assume**: $\lambda_K(\Sigma_W^{1:T}) \ge c > 0$, a.s.. Remark: if $\min_k \tilde{\theta}^*_k \geq c > 0$, this holds for large enough n, \mathcal{T} with high probability.

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Then $\boldsymbol{W}^{1:T}$ is recovered by projection of $\boldsymbol{\Pi}^{1:T}$ onto the span of $A^*.$

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Post-SVD normalization: Compute $\mathbf{R} \in \mathbb{R}^{p \times (K-1)}$: for $i \in [p]$ and $k \in [K-1]$,

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[\bm{R}]_{ik} = \frac{[\bm{U}]_{i(k+1)}}{[\bm{U}]_{i1}}.
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Given $\Pi^{1:T}$, A^* is exactly recovered following these steps (Ke, Wang 2024): Pre-SVD normalization: Compute $\Pi_* := M_*^{-1/2} \Pi^{1:T}$ where

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\boldsymbol{M}_{*} = (nT)^{-1} \text{diag}\left(\boldsymbol{\Pi}^{1:T} \cdot \boldsymbol{1}_{nT}\right).
$$

- SVD: of $\Pi_* := U\Sigma V^\top$ which satisfies rank $(\Pi_*) = K$ a.s..
- *Post-SVD normalization:* Compute $\mathbf{R} \in \mathbb{R}^{p \times (K-1)}$: for $i \in [p]$ and $k \in [K-1],$

$$
[\bm{R}]_{ik} = \frac{[\bm{U}]_{i(k+1)}}{[\bm{U}]_{i1}}.
$$

 $[{\boldsymbol R}]_{1.}, \ldots, [{\boldsymbol R}]_{p.}$ are located in a simplex

$$
G_{\eta}:=\left\{x:x=\sum_{k=1}^{K}\alpha_{k}\eta_{k},\ \forall k\in[K],\ \alpha_{k}\geq0\ \sum_{k=1}^{K}\alpha_{k}=1\right\}.
$$

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- Pre-SVD normalization
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$$
[\boldsymbol{R}]_{i.} = \sum_{k=1}^{K} [\boldsymbol{\Lambda}]_{ik} \boldsymbol{\eta}_k,
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\sum_{k=1}^K [\mathbf{\Lambda}]_{ik} = 1 \text{ and } [\mathbf{\Lambda}]_{ik} \geq 0 \text{, for } k \in [K].
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Word-topic matrix estimation: Define $\Gamma := M_{*}^{1/2}$ diag $([U]_{.1})\Lambda$. Normalize each column of Γ by its \mathbb{L}_1 norm. The resulting matrix is A^* .

 $\ddot{}$

Dynamic Latent Factors: Estimators

We define $\hat{\theta}$, estimator of $\tilde{\theta}^*$, as the empirical mean of the recovered $\left(W_j^{t+1}\right)$ j,t :

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\hat{\theta} := \frac{1}{n(T-1)} \sum_{j=1}^{n} \sum_{t=1}^{T-1} W_j^t.
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$$

We estimate $1 - c^*$ by the normalized sum of scalar products:

$$
\widehat{(1-c)} := \frac{\sum_{t=1}^{T-1} \sum_{j=1}^{n} \left\langle W_j^{t+1} - \overline{W}^{+1}; \ W_j^{t} - \overline{w} \right\rangle}{\sum_{t=1}^{T-1} \sum_{j=1}^{n} \left\| W_j^{t} - \overline{W} \right\|_2^2},
$$

$$
\overline{W}^{+1}:=\frac{1}{n(T-1)}\sum_{t=1}^{T-1}\sum_{j=1}^n W_j^{t+1} \text{ and }\overline{W}:=\frac{1}{n(T-1)}\sum_{t=1}^{T-1}\sum_{j=1}^n W_j^{t}.
$$

Using the variance of the stationary sequence and the explicit expression of the matrix $Σ$, we see that:

$$
\text{Tr}(\mathbb{V}(w_j^t)) = \frac{c^*}{2 - c^*} \frac{1 - ||\tilde{\theta}^*||_2^2}{\alpha + 1}.
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$$
\hat{\alpha}=\frac{\hat{c}}{2-\hat{c}}\frac{1-\|\hat{\theta}\|_2^2}{\mathcal{V}}-1,\quad\text{where}\quad \mathcal{V}:=\frac{1}{\mathsf{n}(\mathcal{T}-1)}\sum_{t=1}^{\mathcal{T}-1}\sum_{j=1}^{\mathsf{n}}\big\|\mathsf{w}_j^t-\overline{\mathsf{w}}\big\|_2^2\,.
$$

For any N, n and T large enough, with probability at least $1-\dfrac{\mathcal{C}_1}{nT}$:

$$
\max\left\{\left\|\hat{\theta}-\tilde{\theta}^*\right\|_2, |(\widehat{1-c})-(1-c^*)|, |\hat{\alpha}-\alpha^*| \right\} \leq \mathcal{C}_2 \cdot \sqrt{\frac{\log(n\mathcal{T})}{n(\mathcal{T}-1)}},
$$

where C_1 , $C_2 > 0$ are explicit constants, free of the dimensions appearing in the model.

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 \textbf{D} Deviation of $\hat{M} := (nT)^{-1}$ diag $\left(\textbf{Y}^{1:T} 1_{nT}\right)$ from $M_* := (nT)^{-1}$ diag $\left(\mathbf{\Pi}^{1:T} 1_{nT}\right)$

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$$
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$$
 from
\n- $\mathbf{M}_* := (n\tau)^{-1} \text{diag}\left(\mathbf{\Pi}^{1:T} \mathbf{1}_{n\tau}\right)$
\n- Deviation of $[\hat{U}]_{.1}, \ldots, [\hat{U}]_{.K}$ from $[\mathbf{U}]_{.1}, \ldots, [\mathbf{U}]_{.K}$
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- **2** Deviation of $[\hat{U}]_1, \ldots, [\hat{U}]_K$ from $[U]_1, \ldots, [U]_K$
- ³ Behaviour of the vertex hunting algorithm with noisy entries.

For N, n and T large enough, there exists χ , a positive constant only depending on K, such that with probability at least $1 - \dfrac{8}{nT}$:

$$
\sum_{i=1}^p \left\|[\hat{A}]_{i.} - [A^*]_{i.}\right\|_1 \leq \chi \sqrt{\frac{p \log(nT) + p^2}{nT(N-2)}} p(1+p)(1+\max_{x \in \mathcal{G}_{\eta}} \|x\|_2).
$$

For N, n and T large enough, and fixed number of topics K and of the vocabulary size p, with probability at least $1 - \frac{C}{nT}$:

$$
\max \left\{ \left\| \hat{\theta} - \tilde{\theta}^* \right\|_2, |(\widehat{1 - c}) - (1 - c^*)|, |\hat{\alpha} - \alpha^*| \right\}
$$

$$
\leq \mathcal{O}\left(\sqrt{\frac{\log(n\tau)}{n(\tau - 1)}} + \sqrt{\frac{\log(n\tau)}{N}}\right).
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The convergence rates show an additive behavior of the noise contained at different levels in the model.

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The bounds are driven by the Dirichlet noise and by the multinomial noise.